

http://www.trafficware.com



http://www2.naztec.com/sites/default/files/documents/training/ simulator/mm.htm



TS2 Keyboard Interface







Main Menu & Software Notation

 To get to the main Menu from the TS2 controller use the MAIN/DISP Key
 Naztec uses the



Naztec uses the notation MM for Main Menu

Main Menu 1.Controller 4.Scheduler 7.Status 2.Coordinate 5.Detectors 8.Login,Utils 3.Preempts 6.Comm 9.CLP Master



Software Notation (continued)

- Using MM to indicate Main Menu allows us to tell the user how to navigate to the appropriate screen.
- To Program Phase timing must type— MM→1→1→1 to get to screen on right

Times	Ø.1.	2	3	4	5	6	7	8	->
Min Grn	255	5	3	5	3	5	3	5	
Gap,Ext	25.5	1.0	1.0	1.0	1.0	1.0	1.0	1.0	
Max 1	255	25	25	25	25	25	25	25	
Max 2	255	50	50	50	50	50	50	50	
Yel Clr	25.5	3.0	3.0	3.0	3.0	3.0	3.0	3.0	
Red Clr	25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Walk	255	5	0	5	0	5	0	5	
Ped Clr	255	10	0	10	0	10	0	10	
Red Revt	25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Add Init	25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Max Init	255	0	0	0	0	0	0	0	
Gap Redu	ICe								
Time B4	255	0	0	0	0	0	0	0	
Cars B4	255	0	0	0	0	0	0	0	
Time To	255	0	0	0	0	0	0	0	
ReducBy	25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Hin Gap	25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
DyMaxLin	255	0	0	0	0	0	0	0	
Nax Step	255	0	0	0	0	0	Q	0	

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Software Notation-What you see

 $MM \rightarrow$

 $1 \rightarrow$

 $1 \rightarrow$

	Main Menu	
1.Controller	4.Scheduler	7.Status
2.Coordinate	5.Detectors	8.Login,Utils
3.Preempts	6.Comm	9.CLP Master

Co	nt	r	21	1,
a.	1000 TO		- 1-	

1.Phases 4.Flash 2.Unit,Ring 3.Chan,SDLC 6.Alarms

зr. 5.0verlaps

7.Enable Run 8.TempAlrt,Lamp 9.Light Rail

	PHASES	
1.Times	4.Ring,Start,Concur	7.Times+
2.Options	5.Call,Inh,Redirect	8.Copy
3.0ptions+	6.Alt Progs+	9.AdvWarn

Times Ø.1	2	3	4.	5	6	7	8	->
Min Grn 255	5	3	5	3	5	з	5	
Gap,Ext 25.5	1.0	1.0	1.0	1.0	1.0	1.0	1.0	
Max 1 255	25	25	25	25	25	25	25	
Max 2 255	50	50	50	50	50	50	50	
Yel Clr 25.5	3.0	3.0	3.0	3.0	3.0	3.0	3.0	
Red Clr 25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Walk 255	5	0	5	0	5	0	5	
Ped Clr 255	10	0	10	0	10	0	10	
Red Revt25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Add Init25.5	0.0	0.0	0.6	0.0	0.0	0.0	0.0	
Max Init 255	0	0	0	0	0	0	0	
Gap Reduce								
Time B4 255	0	0	0	0	0	0	0	
Cars B4 255	0	0	0	0	0	0	0	
Time To 255	0	0	0	0	0	0	0	
Reducey 25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Min Gap 25.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
DyMaxLim 255	0	0	0	0	0	0	0	
Max Step 255	0	0	0	0	0	0	0	



Editing Data

- Data on specific screens can be edited based on field type
 - Toggle field is On/Off entry denoted by an "X" if enabled or a "." if disabled
 - Numeric Field is numeric data that can be
 - Whole numbers
 - Decimal Numbers
 - Date/Time info



Toggle field

- Typing MM→1→1→2 brings you to the Phase Options Screen
- For example Phase enable is a toggle field
- To enable a phase move the cursor to that phase and type any number---an "X" will appear

Options Ø	1.	.2.	.3.	.4.	.5.	.6.	.7.	.8	->
Enable Ø	X	Х	Х	ж	Х	х	Х	х	
Min Recall	÷.,	Х		-		Х			
Max Recall				-					
Ped Recall	÷.,								
Soft Recall				-					
Lock Calls	÷.,	Х				Х			
Auto Flash Entry	-			х				х	
Auto Flash Exit	÷.,	Х				Х			
Dual Entry		Х		х		х		х	
Enable Simul Gap	÷.,	Х		х		Х		Х	
Guarantd Passage				-					
Rest In Walk		Х				Х			
Condit'l Service				-					
Non-Actuated 1									
Non-Actuated 2				-					
Added Init Cald	c S	S	S	S	S	S	S	S	



Numeric Field

- Type MM→1→1→1 to get to Phase Timing screen
- Cursor over to appropriate timing data
- Enter numeric data (right justified)
- ENTR or cursor movement(arrow key) will enter data

Times (1.1.	2	3	4	5.	6.	7	8	->
Min Grn 2	255	5	3	5	3	5	З	5	
Gap,Ext 2	5.5	1.0	1.0	1.0	1.0	1.0	1.0	1.0	
Max 1 2	255	25	25	25	25	25	25	25	
<u>Max 2</u> 2	255	50	50	50	50	50	50	50	
Yel Clr 25	5.5	3.0	3.0	3.0	3.0	3.0	3.0	3.0	
Red Clr 25	5.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Walk 2	255	- 5	0	5	0	5	0	5	
Ped Clr 2	255	10	0	10	0	10	0	10	
Red Revt25	5.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Add Init25	5.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Nax Init 2	255	0	0	0	0	0	0	0	
Gap Reduce									
Time 84 2	255	0	0	0	0	0	0	0	
Cars B4 2	255	0	0	0	0	0	0	0	
Time To 2	255	0	0	0	0	0	0	0	
ReducBy 25	5.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Hin Gap 25	5.5	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
DyMaxLim 2	255	0	0	0	0	0	0	0	
Nax Step 2	255	0	Q	0	0	Q	Q	Q	



Left & Right Menus



The "->" symbol indicates a "Left menu" has been selected ("<-" indicates a Right Menu has been selected)

- Only a limited amount of Data can be displayed on the on the front panel
- If you see a --> use the cursor and move cursor past the right boundary to get to the next page
- If you see a <-- use the cursor and move cursor past the left boundary to get to the previous page



Other Field Types

Set Date	& Time			
	Date	Day	Time	Secs
Current	05-29-01	TUE	02:44	27
Set To	00-00-00		00:00	00

- Selection field are multiple choice type entries toggled by any numeric key such as day of week entries or Flash entries
- One numeric key will toggle through each choice



Select/Proceed Fields

- Cursor will stop to allow the user to issue a command
- Usually see on warning screens or inside menus
- Follow the instructions on the screen

CAUTION: This function erases ALL operator programmable settings -press ENTR to continue, press ESC to go back...



Special Keys-ESC



• Escape Key

- Causes the controller to exit the active screen and go to previous screen
- If ESC is pressed prior to saving data via the ENTR key—a warning message is posted to allow user to save data before going to prior screen
- Continued pressing of ESC will bring user to Main Menu



Special Keys-Enter



• ENTR for TS2,

- Process the current field (i.e. saves data to memory
 - Select field-loads the screen or takes desired action
 - Proceed field- correlates to a Yes



Display Control



• Use MAIN/DISP for TS2,

- Allows user to quickly move to the main menu
- Will also turn on display Backlight if hit once in Main menu



Alternate Function



- ALT FCN for TS2
- Provides access to various features such as help or default status
- Used in combination with other key
- The following few slides shows the Alternate Functions



ALT FCN, ALT FCN Help Screen

- Load content sensitive Help from any screen that you are in.
- Repeating Alt FCN ALT FCN will bring you back to the original timing

TS2 Keystrokes





ALT FCN, ESC Restore Clear Field

 Restore previous (original) data value to field that user just edited data prior to pressing the ENTR key

• Only valid for last data entry

TS2 Keystrokes





ALT FCN, MAIN/DISP Back Light Control

Toggle on/off the back light for the display





Alt FCN, 1 Key Calls Mode



TS2 Keystrokes

- Activated from Timing Status screen Only (I.e. $MM \rightarrow 7 \rightarrow 1$)
- Testing purpose only
- •To apply:
 - Type ALT FCN then 1
 - Enter 2 digits for Phase number (01,02....16)
 - Then enter Down Arrow Key to apply Phase call or Up Arrow key to remove Phase call
- Once leave Phase status screen the calls are automatically removed



Overview Status Screen ALT FCN, 9



Controller	Monitor	Cabinet	System
TIMING	NO DATA	I NO DATA	ONLINE
COORD	1	1	1
	1	1	1

Display Overview Status Screen
General Operating Status of controller
Logs you off if you enter an access code
Can also be accessed via the following keystrokes: MM→7→9→5



STD 8 Phase assignments





STD8 Ring Barrier



STD8 Operation - Min Recalls on Phases 1, 2, 7 and 8 Max Recalls on Phases 3, 4, 5 and 6



Controller Timing MM $1 \rightarrow 1 \rightarrow 1$

	Main Menu	
1.Controller	4.Scheduler	7.Status
2.Coordinate	5.Detectors	8.Login,Utils
3.Preempts	6.Comm	9.CLP Master

	Controller	
1.Phases	4.Flash	7.Enable Run
2.Unit,Ring	5.0verlaps	8.TempAlrt,Lamp
3.Chan,SDLC	6.Alarms	9.Light Rail

	PHASES	
1.Times	4.Ring,Start,Concur	7.Times+
2.0ptions	5.Call,Inh,Redirect	8.Copy
3.0ptions+	6.Alt Progs+	9.AdvWarn





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Times $\emptyset.1...2...3...4...5...6...7...8 \rightarrow$ <u>Min Grn</u> 255 5 3 5 3 5 3 5 3 5 <u>Gap,Ext</u> 25.5 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 <u>Max 1</u> 255 25 25 25 25 25 25 25 25 <u>Max 2</u> 255 50 50 50 50 50 50 50 50 <u>Yel Clr</u> 25.5 3.0 3.0 3.0 3.0 3.0 3.0 3.0 3.0 <u>Red Clr</u> 25.5 0.0 0.0 0.0 0.0 0.0 0.0 0.0 <u>Walk</u> 255 5 0 5 0 5 0 5 0 5 <u>Ped Clr</u> 255 10 0 10 0 10 0 10 <u>Red Revt</u> 25.5 0.0 0.0 0.0 0.0 0.0 0.0 0.0



- Non Density refers to Basic timing Functions
- Minimum Intervals are always guaranteed
- Min Green-Same as Initial Green





• Gap Extension

- Begins timing down when goes to the phase
- Actuations for the phase reset this and force it to retime
- Expires when reach Max or if phase is Forced off Max
- Will rest in phase if there is no opposing call
- Once Opposing call occurs will go to that next phase
- Max 1-Maximum Time to allow for phase
 - Max Timer will start upon first opposing call and will be reset if opposing call disappears
- Max 2- can change Max to this time on a time of day basis





Non-Density Phase Timing Functions Yel Clr- Yellow time Red Clr- All red time Like Min times clearance intervals are guaranteed



Pedestrian Timing

Walk- Walk Time Ped Clr- Pedestrian Clearance Min Green will extend to max extent of Ped Clearance Time





•Red Revert

• Red Revert Interval will follow Yellow Timer whenever the signal indication is returning to the phase just serviced.

• This is the amount of time that the phase is required to be red before reservice.



 Add Init
 25.5
 0.0
 0.0
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- These timers control traffic based on Traffic Actuations and are not guaranteed
- Variable Initial or Added Initial
 - Times concurrently with initial
 - Is increased by each vehicle counted during yellow/red
 - Must be set for each detector
 - Limit is set by Max Init
 - Initial time becomes the greater if Initial or Max Initial



- Variable Initial or Added Initial
 - Times concurrently with initial
 - Is increased by each vehicle counted during yellow/red
 - Must be set for each detector
 - Limit is set by Max Init
 - Initial time becomes the greater if Initial or Max Initial





For Gap reduction Programming Time Before or Cars Before Reduction

- •Time that occurs or # of vehicles that are counted before reduction begins
- Resets if opposing demand goes away



- Once Reduction begins
 - Max Gap (Gap,Ext) is reduced to Min Gap in "Reduce By" steps over the period programmed as "Time to Reduce"




Density Phase Timing Functions

•OR Linear Reduction will occur if the user just programs "Time to Reduce"





Density Phase Timing Functions

- PHASE DYNAMIC MAX LIMIT Dynamic Max Limit determines either the upper or lower limit of the running max (0-255 sec) during dynamic max operation.
- Normal maximum (MAX1, MAX2) determines the other limit.
- If the dynamic max limit is larger than the normal maximum, it is then the upper limit, if it is smaller, it becomes the lower limit.
- Maximum recall or a failed detector that is assigned to the associated phase disables dynamic max operation for the phase.



Density Phase Timing Functions

• PHASE DYNAMIC MAX STEP - Dynamic Max Step determines the automatic adjustment to the max time (0-255 sec). When a phase maxes out twice in a row, (and for each successive max out afterwards) one dynamic step value is added to the running max. After two gap outs in a row, each subsequent successive gap out reduces the running max by one dynamic step.





Phase Options $MM \rightarrow 1 \rightarrow 1 \rightarrow 2$

Main Menu

- 1.Controller 4.Scheduler 7.Status
- 2.Coordinate 5.Detectors 8.Login,Utils
- 3.Preempts 6.Comm 9.CLP Master

	Controller	
1.Phases	4.Flash	7.Enable Run
2.Unit,Ring	5.0verlaps	8.TempAlrt,Lamp
3.Chan, SDLC	6.Alarms	9.Light Rail

1.Times 2 Options	PHASES 4.Ring,Start,Concur 5.Call Inb Redirect	7.Times+)ptions Ø.,	.1.	.2.	.3.	.4.	.5.	.6.	.7.	.8 -	->
2 Options	6 31t Proget	0 Schellara	Enable Ø	х	х	х	х	х	х	х	х	
3.0ptions+	6.AIU PIOUST	9.Advwarn	Min Recall									
			Max Recall	•	•	•	•					
			Ped Recall	•	•	•	•				•	
			Soft Recall	•	•	•	•		×.		÷.,	
			Lock Calls			•	•	•	•		× .	
			Auto Flash Entry							•	1	
			Auto Flash Exit		•			•		•		
			Dual Entry			•					10	
			Enable Simul Gap		•			•		•		
			<u>Guarantd Passage</u>	•	•	•			1			
			<u>Rest In Walk</u>					•		•		
			Condit'l Service		•	•			÷.,			
			Non-Actuated 1	•	•	•	•				•	
			Non-Actuated 2		•	•	•	•				
			Added Init Calc	s	S	s	S	S	S	S	S	



• Enable Ø-Vehicle Phases Permitted

- Min Recall- Vehicle Recall based on the Min time on each phase designated
- Max Recall- Vehicle Recall based on the Max time on each phase designated
- Ped Recall- Recall based on the Pedestrian Time (Walk + Don't Walk) on each phase designated



•Soft Recall-

- Designated phase will be called if there is no demand on any other phase in the Controller
- A soft recall will not start the MAX or GAP timers for phases currently Green and having demand
- Lock Calls-Phases that lock detector memory at beginning of Yellow



- Auto Flash Entry- When running time clock flash; the controller services the designated entry phases, clears to all red, then proceeds with flashing operation.
- Auto Flash Exit- When exiting time clock flash to resume normal Operation the controller proceeds to the beginning of phases designated as these exit phases.
- Dual Entry Ø- Will be run only when cross barrier and no other Ø in the same ring has a demand



• Enable Simultaneous Gap

- Controller is not allowed to cross barrier unless Current GREEN phases in both rings GAP out or MAX out.
 - If not set, the controller is permitted to cross the barrier if one ring GAPS out and the other MAX's out
 - If set the passage timer will be reset on the phase with this feature enabled while it's concurrent phase is being extended.
 - This is a very important setting for the through movements during actuated operation. If enable simultaneous gap is not set for the main street phases, you can easily create a situation when one main street phase has gaped when the leading edge of a platoon of vehicles begins hitting the detector. The platoon cannot extend the phase because it has already gapped out and enable simultaneous gap is not set for this phase



Simultaneous Gap Example

- Assume that simultaneous gap is enabled for main street phase Ø2, but not for phase Ø6.
- If Ø2 gaps out while Ø6 is still being extended, the Ø2 Passage timer will reset if enable simultaneous gap is set and Ø2 receives a new call.
- However, if Ø6 gaps out while Ø2 is still being extended, the Ø6 Passage timer will NOT reset because Enable Simultaneous Gap is NOT set even if Ø6 receives a new vehicle call.



STD 8 Phase assignments



- Rest in Walk
- Phases declared as Rest in Walk will not time the Ped Clearance interval until an opposing call occurs
- Typically works with Artery Ped Recycle to allow pedestrians movement to run as long as possible in the artery movement

Red Interval	← Min Green	\longrightarrow	Extend	Y
Don't Walk	Don't Walk Walk		d Clearance	Don't Walk
↑ ↑ V P	Call From	Conflicting Ø		Time

Phase Options + $MM \rightarrow 1 \rightarrow 1 \rightarrow 3$

- These are Naztec Specific Options that enhance controller operations
- NTCIP definitions are generic between manufacturers and our user base requested other operational parameters that we incorporated in our software

• Reservice Phase

- Used with Conditional Service
- Under conditional service
 - Once a phase ends and the controller goes back to a conditional service phase—it can't go back to the phase it left
- If a phase is declared as a Reservice Phase it can be reserved after conditionally serving the lead phase

• Red Rest-Rest in red in absence of conflicting call

- Forces phase to time out
- If Recall or Hold is set then there is No Red Rest
- Max II- allows the declared Phases to run the Max II timer

• Ped Delay & Green Ped Delay -

- Works together to delay the start of the green (Advanced Ped) or delay the Walk interval from timing
- Ped Delay is the Phase
- Green Ped Delay is the time to delay
- Included in Coordination Diagnostics to insure that split time is not compromised.

$\bullet \text{Conflicting } \varnothing$

- This Designated phase will not be allowed to run with the phase it conflicts with—must be used with concurrent phase in other ring
- Example Program

Ring 1	1	1	2	3	4
Ring 2	6	6	5	7	8

Options+	ø.	.1.	.2.	.3.	.4.	.5.	.6.	.7.	.8 ->	
Conflicting	ø	5	0	0	0	0	٥	0	0	
Conflicting	ø	0	0	ŏ	õ	õ	ŏ	0	ŏ	
Omit Yel, Yel	ø	0	0	0	0	0	0	0	0	
Ped Out/Ovrlp	ø	0	0	0	0	0	0	0	0	
StartYel,Next	ø	0	0	0	0	0	0	0	0	

Phase 5 can't be run with Phase 1
Useful in forcing left turns on same road to be served separately

Rings Sequences & Phase Concurrency

- Various menus control these features
 Naztec software supports 16 phases assigned to up to 4 rings.
- The Controller software uses the ring sequences and concurrency definitions to determine the order that phases are run.
- Various Phase modes may be selected

Phase Mode

STD8 – Standard 8 Phase

- QSeq Quad Sequential
- 8Seq 8 Phase Sequential
- DIA Texas Diamond

USER – User defined phase mode

Ring Sequence / Concurrency

 Ring 1
 1
 2
 3
 4

 Ring 2
 5
 6
 7
 8

2

6

Ring 1 1 Ring 2 5

Ring 1	1	2	3	4	5	6	7	8
--------	---	---	---	---	---	---	---	---

4

3

USER sequence based on the Texas Diamond Specification

8

Ring 1	1	2	3	4	5	6	7	8
Ring 2	11	12	13	14	0	0	0	0
Ring 3	15	0	0	0	0	0	0	0
Ring 4	16	0	0	0	0	0	0	0

Unit parameters $MM \rightarrow 1 \rightarrow 2 \rightarrow 1$

• Choose Phase Mode as discussed on last slide

UNIT	PARAN	IETERS	
StartUp Flash(s)	0	Red Revert	3.0
Backup Time(s)	0	Auto Ped Clr	OFF
Phase Mode	STD8	Diamond Mode	4Ø
Local Flash Start	OFF	<u>Start Red Tm</u>	0.0
		<u>Min PedClr Tm</u>	0
<u>Allow <3 sec Yel</u>	OFF	Allow SkipYel	OFF
Disable Init Ped	OFF	Free Ring Seg	1
StopTm Over Prmpt	OFF	<u>Invert RailIn</u>	OFF
<u>Feature Profile</u>	0	<u>Enable Run</u>	ON
<u>Display Time</u>	30	<u>Tone Disable</u>	ON
<u>TS2 Det Flts</u>	ON	SDLC Retry Tm	0
<u>Max Cycle Tm</u>	0	CycFlt Actn Al	LARM
<u>Max Seek Trak</u>	0	Max Seek Dwell	L 0

Unit parameters $MM \rightarrow 1 \rightarrow 2 \rightarrow 1$

• Choose Phase Mode as discussed on last slide

UNIT	PARAN	IETERS	
StartUp Flash(s)	0	Red Revert	3.0
Backup Time(s)	0	Auto Ped Clr	OFF
Phase Mode	STD8	Diamond Mode	4Ø
Local Flash Start	OFF	<u>Start Red Tm</u>	0.0
		<u>Min PedClr Tm</u>	0
<u>Allow <3 sec Yel</u>	OFF	Allow SkipYel	OFF
Disable Init Ped	OFF	Free Ring Seg	1
StopTm Over Prmpt	OFF	<u>Invert RailIn</u>	OFF
<u>Feature Profile</u>	0	<u>Enable Run</u>	ON
<u>Display Time</u>	30	<u>Tone Disable</u>	ON
<u>TS2 Det Flts</u>	ON	SDLC Retry Tm	0
<u>Max Cycle Tm</u>	0	CycFlt Actn Al	LARM
<u>Max Seek Trak</u>	0	Max Seek Dwell	L 0

Ring Concurrency, Startup $MM \rightarrow 1 \rightarrow 1 \rightarrow 4$

- Must define what phases are concurrent
- Also can define how you want to start up the controller
 - Red-Phase will startup in Red interval
 - RedCl- startup in Red interval using Start Red Time parameter (MM→1→2→1), i.e. all phases will startup in red
 - Yellow- Phase will startup in yellow interval
 - Green-Phase will startup in green interval (no peds)
 - Walk- Phase will startup in green & walk intervals

ø	Rg	<u>Start</u>	Co	ncu	rre	nt	Øs				
1	1	RED	5	6	0	0	0	0	0	0	
2	1	RED	5	б	0	0	0	0	0	0	
3	1	RED	7	8	0	0	0	0	0	0	
4	1	RED	7	8	0	0	0	0	0	0	
5	2	RED	1	2	0	0	0	0	0	0	
6	2	RED	1	2	0	0	0	0	0	0	
7	2	RED	3	4	0	0	0	0	0	0	
8	2	RED	3	4	0	0	0	0	0	0	
9	0	RED	0	0	0	0	0	0	0	0	
10	0	RED	0	0	0	0	0	0	0	0	
11	0	RED	0	0	0	0	0	0	0	0	
12	0	RED	0	0	0	0	0	0	0	0	
13	0	RED	0	0	0	0	0	0	0	0	
14	0	RED	0	0	0	0	0	0	0	0	
15	0	RED	0	0	0	0	0	0	0	0	
16	0	RED	0	0	0	0	0	0	0	0	

STD 8 Phase assignments

STD8 Ring Default Sequences Every Lead/Lag Combination

Seq #	Phase Seq.							
1	1	2	3	4				
I	5	6	7	8				
2	1	2	3	4				
2	6	5	7	8				
3	2	1	3	4				
<u> </u>	5	6	7	8				
Δ	2	1	3	4				
4	6	5	7	8				
5	1	2	3	4				
5	5	6	8	7				
6	1	2	3	4				
0	6	5	8	7				
7	2	1	3	4				
I	5	6	8	7				
8	2	1	3	4				
0	6	5	8	7				

Seq #	Ph	ase	Seq		
0	1	2	4	3	
5	5	6	7	8	
10	1	2	4	3	
10	6	5	7	8	
11	2	1	4	3	
	5	6	7	8	
12	2	1	4	3	
12	6	5	7	8	
13	1	2	4	3	
15	5	6	8	7	
14	1	2	4	3	
14	6	5	8	7	
15	2	1	4	3	
15	5	6	8	7	
16	2	1	4	3	
10	6	5	8	7	

User Mode Example

• Programming up to a 16 phase sequence

- The software only allows for 8 phases per each ring.
- Example: To get 12 Phases just continue to next ring

Seq#	Ring	Sequence.of.Phases				5			
1	1	7	9	15	4	2	3	12	5
1	2	->1	6	11	14	0	0	0	0
1	3	0	0	0	0	0	0	0	0
1	4	0	0	0	0	0	0	0	0

Overlap Programming

Main Menu

- 1.Controller 4.Scheduler 7.Status
- 2.Coordinate 5.Detectors 8.Login, Utils
- 3.Preempts 6.Comm 9.CLP Master

	Controller	
1.Phases	4.Flash	7.Enable Run
2.Unit,Ring	5.0verlaps	8.TempAlrt,Lamp
3.Chan,SDLC	6.Alarms	9.Light Rail

01	70	*	1	-	n	•
0	ve	-	+	a	μ	2

- 1.General Parms
- 2.Program
- 3.Status

$Overlaps - MM \rightarrow 1 \rightarrow 5$

- Naztec Provides 16 fully programmable Overlaps that may be assigned to any load switch in the cabinet
- An overlap is a customized channel output driven by one or more included phases
- It is a way to allow a movement that wouldn't normally run to occur if there are no conflicts

Overlap Example # 1

Overlap 1 =

Ø4 + Ø5

Its Load Switch Output will turn green whenever the software is running Phases 4 or 5 and will stay green while transitioning from Phase 4 to 5.

Overlap Example # 2

Consecutive Included \emptyset 1+ \emptyset 2 in the Same Ring

Non-consecutive Included Ø 1+6 in Separate Rings

Overlap Example # 3

- Overlaps may be defined with any number of phases in the same ring as shown below.
- This feature is useful in sequential phase operation (8SEQ or USER phase mode) to create signal displays that overlap any number of phases in the sequence.

When Included Phases Are Not Consecutive, the Overlap Will Time Multiple Clearances During the Sequence

Overlap Program Selection & Configuration

 $\mathsf{MM} \rightarrow 1 \rightarrow 5 \rightarrow 2$

- ()ve	r1	ap (
			-

- 1.Program Parms
- 2.Confl Prog+

 $\mathsf{MM} \rightarrow 1 \rightarrow 5 \rightarrow 2 \rightarrow \# \rightarrow 1$

 Ovrlp G
 Øs....

 Included Øs
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Engineered by **[N] Naztec**

- Included Phases
 - Max of 8 Phases (Parent Phases) can be assigned to the overlap

• Modifier Phases

- Max of 8 phases can be assigned to alter the overlap operation
- Based on Overlap Type

Overlap Program Selection & Configuration

- Overlap Green Extension
 - Extends the Overlap green also known as Trailing Green (0-255 sec)
 - Example is Double Clearance
 - Occurs once included phase terminates and control goes to a non included phase
- Overlap Yellow Clearance (0-25.5 sec) & Overlap Red Clearance
 - Must be programmed if Overlap Green Extension is programmed
 - Doesn't need to be programmed if program Parent Phase Clearance feature (MM→1→5→1) is set to "ON"

Normal

- The overlap is green when an included phase is green, or an included phase is timing yellow/red clearance and an included phase is next
- The overlap is yellow when an included phase is yellow and an included phase is not next
- The overlap is red when the overlap green and yellow are not on
- The overlap is dark (all outputs off) when a modifier phase is on during it's green, yellow or all-red interval

General Overlap Parameters $MM \rightarrow 1 \rightarrow 5 \rightarrow 1$

General Overlap Parameters

- Conflict Lock Enable is used with Lock Inhibit
- Conflict Lock Enable
 - On-Controller will suppress all conflicting phases (veh & peds) until overlap completes timing overlap Green extension and clearance intervals
 - Off- Conflicting phases (veh & peds) will proceed while the overlap is timing these intervals

General Overlap Parameters

• Parent Phase Clearance

- On- Overlap clearances are timed using Parent Phase timings (MM→1→1→1)
- Off- the green extension, yellow and all-red clearances for each overlap are used


Overlap +

$\mathsf{MM} \rightarrow 1 \rightarrow 5 \rightarrow 2 \rightarrow$

Enter overlap #

→2

Ovrlp G	Øs.								
Confl Øs	0	0	0	0	0	0	0	0	
Confl Ovrlps	0	0	0	0	0	0	0	0	
Confl Peds	0	0	0	0	0	0	0	0	
Lead Grn OFF	Del	ay	0						

Conflicting phases, pedestrian and overlaps terminate an overlap when the conflicting phase, pedestrian movement or overlap is next and continue to suppress the overlap while the conflicting phase, pedestrian movement or conflicting overlap is timing green and yellow clearance.



Conflict Ped Example





$MM \rightarrow 1 \rightarrow 5 \rightarrow 3$ Overlap Status Display

Overlap	. A1	B2	c3	D4	E5	F6	G7	.H8 ->
Interval								
Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Ø/Intvl	2/0	GRN	6/0	GRN	0/.		0/-	



Detector Programming ● Use MM→5

	DETECTORS T	
1.Veh Parms	4.Ped Parms	7.Status
2.Veh Options	5.Alt Progs	8.V/0-Speed
3.Veh Parms+	6.Phas Recall	9.Copy



Vehicle Parameters $MM \rightarrow 5 \rightarrow 1$

• Call Ø - Actuates during red

- Actuates during green if Extend or Queue is set
- Switch $\boldsymbol{\varnothing}$ is extended when
 - Call \emptyset is Red or yellow and the switch \emptyset is green
 - Used for protected/permitted lefts to call & extend a protected left turn Ø after cross street is serviced

Det#	Call	Switch	Delay	Extend	Queue ->
1	1	0	0.0	0.0	0
2	64	16	25.5	25.5	255
3	3	0	0.0	0.0	0
4	4	0	12.0	0.0	0
5	5	0	0.0	0.0	0
6	6	0	0.0	0.0	0
7	7	0	0.0	0.0	0
8	8	0	12.0	0.0	0
64	1	0	0.0	0.0	0



Vehicle Parameters MM→5→1

• Delay Ø- Delay time before actuation (during Red)

- Extend Ø- Extend actuation time during Green
- Queue Limit- Time that the detector is active during green-once this time expires the detector is ignored.

Det#	Call	Switch	Delay	Extend	Queue ->
1	1	0	0.0	0.0	0
2	64	16	25.5	25.5	255
3	3	0	0.0	0.0	0
4	4	0	12.0	0.0	0
5	5	0	0.0	0.0	0
6	6	0	0.0	0.0	0
7	7	0	0.0	0.0	0
8	8	0	12.0	0.0	0
64	1	0	0.0	0.0	0



Vehicle Options $MM \rightarrow 5 \rightarrow 2$

 Each Detector can be programmed as a Calling, Extension, Queue, Added Initial, Red Lock, Yellow Lock Volume and Occupancy detector

Det#	Call	Extend	Queue	Add.I	<u>nit</u> ->	in the second				
1	x	х		х	Extend	Selected				
2	x		x	х	Queue S	Selected				
3	x	x	х	х	Extend	Selected				
- 4	x	x		х						
5	х	х		х		<- Det#	Red.Lock	Yel.Lock	0ccup	Volum
6	×	х		х		1			X	x
7	x	х		х		2			х	x
						3			х	x
64	х	х				4			x	х
						5			x	х
						6			х	х
						7			х	х
						8			х	х
						9		•	х	х
						64	÷		х	х



Vehicle Option Notes

- Call Option- calls during Ø Red
- Extend- Resets extension timer during green interval & overrides Queue Option
- Queue Extends assigned Ø until gap occurs or green is active longer than Queue Timer
- Added Initial- count during yellow & red

Det#	Call	Extend	Queue	Add. I	nit ->
1	х	x		х	Extend Selected
2	x		x	х	Queue Selected
3	х	x	х	х	Extend Selected
4	x	x		х	
5	х	x		х	
6	x	x		х	
7	х	х		х	
64	х	x		1	



Pedestrian Parameters MM→5→4

Pedestrian Call Phase
Pedestrian Detector Diagnostics
No Activity
Max Presence

• Erratic Counts

Det#	Call	NoAct	MaxPres	ErrCnt
1	16	255	255	255
2	2	0	3	0
3	0	0	0	0
4	4	0	3	0
5	0	0	0	0
6	6	0	3	0
7	0	0	0	0
8	8	0	3	0



Detector Status Screens MM→5→7



(1-16) Det	#	1	9>	
Veh Call					
Veh Alar	m				

Det #	18
Ped Call	
Ped Alarm	



Channel Assignments $MM \rightarrow 1 \rightarrow 3 \rightarrow 1$

- A channel is an output driver that switches 120V AC Power to a signal display
- Channel outputs Red, Yellow & Green via three different output pins
- Channel Types
 - Vehicle
 - Pedestrian
 - Overlap



Channel Assignments $MM \rightarrow 1 \rightarrow 3 \rightarrow 1$

Char	11	L	2 .	3	4	5.	6.	7	. 8→	
P/0]	lp#		9	2	10	11	12	6	13	14
TΣ	vpe –		OLP	VEH	OLP	OLP	OLP	VEH	OLP	PED
Fla	ash		RED	YEL	RED	RED	RED	YEL	RED	DRK
Alt	Hz			Х		•	•	Х	•	
Dim	Grn		•	Х	•	•	•	Х	•	•
Dim	Yel		•	Х	•	•	•	Х	•	•
Dim	Red		Х	Х	Х	Х	Х	Х	Х	•
Dim	Сус	\downarrow	+	-	+	+	+	-	+	+

<- Chan.	.9.	.10.	.11.	.12.	.13.	.14.	.15.	.16
<u>ø/01p#</u>	1	2	3	4	2	4	6	8
Туре	OLP	OLP	OLP	OLP	PED	PED	PED	PED
Flash	RED	RED	RED	RED	RED	RED	RED	RED
Alt Hz	х	х	х	х	х	х	х	х



Time Base Scheduler $MM \rightarrow 4$

- Fully Compliant NTCIP Time of Day Scheduler
- Program the NTCIP Way via Advanced Scheduler Option or....
- Can program Naztec's way via Easy Scheduler
- The Time of Day Database will always reside in Advanced Scheduler

Time Based Scheduler

1.Set Date/Time	4.Day Plan	7.Status
2.Easy Schedule	5.Action Table	8.SplFeat
3.Adv Schedule	6.Parameters	9.More



Theory of Operation

- Each day the controller checks the Advanced Scheduler to determine the most applicable Day Plan.
- If the current day is not specified in the Advanced Schedule, the controller will run "free" in Pattern # 0.
- The controller checks the current Day Plan once per minute to retrieve the current time-of-day action.
- The controller then performs a lookup in the Action Table to determine the active TBC Pattern.
- The TBC Pattern determines the current time-of-day operation of the controller.



Theory of Operation



Selects Day Plan

Time-of-Day Action

the Pattern



Advanced Scheduler

	Day	Month	more	->	<-	1	Date	1			2			3	Day
#	SMTWTFS	JFMAMJJASOND			#	123	4567	890	1234	5678	9012	2345	6789	901	Plan
1	XXXXXXX	XXXXXXXXXXXXXX			1	XXX	xxxx	xxx	xxxx	xxxx	xxx	xxx	xxx	xx	1
2					2										1
3					3										1
4					4										1
5					5										1
6					6										1
7					7										1
95	••••				95								•••		1

The Advanced Scheduler is an annual calendar used for the current year to select the Day Plan for the current day. Choose Day Plans from 1-32.



Advanced Scheduler

- Can select multiple entries for Day month & Date
 - For example you can choose one Day Plan for Sat & Sun each week by programming Day as S.....S
 - You can choose another Day Plan for Monday-Friday each week by programming Day as .MTWTF
- Can have duplicate entries for the same day—controllers chooses the more specific entry
 - Previous slide Entry says run Day Plan 1 every day of the year
 - If you program Day plan 2 for December 25, it will override the previous because it is more specific



Easy Scheduler

• Alternate way of programming the schedule

- Each entry applies to a consecutive range of days, months or days of months
- Range is automatically transferred Advanced Scheduler
- A DOM entry of "**-**" means that a more complex entry has been set up in the Advanced Scheduler

#	Day	Mo:From-Thru	DOM: From-Thru	Plan	
1	ALL	01-12	01-31	1	
2	OFF	00-00	00-00	1	
3	OFF	00-00	00-00	1	
4	OFF	00-00	00-00	1	
5	OFF	00-00	00-00	1	
6	OFF	00-00	00-00	1	
7	OFF	00-00	00-00	1	
95	OFF	00-00	00-00	1	



Day Plan Table

Plan-24	Evt	Time Ac	tn	Evt	Time Ac	tn	
Link: 0	1	00:00	0	2	00:00	0	
	3	00:00	0	4	00:00	0	
	5	00:00	0	6	00:00	0	
	7	00:00	0	8	00:00	0	
	9	00:00	0	10	00:00	0	
	11	00:00	0	12	00:00	0	
	13	00:00	0	14	00:00	0	
	15	00:00	0	16	00:00	0	

- The Scheduler reads the active Day Plan for the current date once per minute to update the current Action.
- The Action drives the active Pattern and controls the state of the special function outputs from the Action Table.



Day Plan Table Parameters

- Time defines the time of day that the associated Action will become active
 Program in military time
- Action (1-100) is the action number (see Action Table).
 - Action "0" is the do nothing action (Not Free!)
 - Good Practice to assign an event and Action at 00:00 (midnight) for every Day Plan called by the Advanced Schedule.
 - Insures that even if the controller date is changed and a new Day Plan is referenced that at least the first Action specified for 00:00 will be selected.



Action Table $MM \rightarrow 4 \rightarrow 5$

• Controls Patterns and 24 special function outputs selected by the current day plan

Actn	Patrn	Aux-12345678	Spec-12345678 ->
1	1		
2	2		
3	3		
4	0		
5	0		
6	254		
7	255		
100	0		



Action Table

 Pattern is a TBC Pattern selected by the current Action #

- Valid Patterns #'s 1-48, 254 is free, 255 Flash
- Aux-12345678- Controls the state of the auxiliary outputs when the action is active
- Spec-12....24 Controls the Special Functions outputs when each action is active